CAN MUSCLE FATIGUE IN WOMEN BE INFLUENCED BY KNEE EXTENSION TASKS IN DIFFERENT RANGES OF MOTION?

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ABSTRACT

Purpose. The present study aimed to compare the strength performance in the one-repetition maximum (1RM) test with a knee extension machine among different ranges of motion (ROMs), and to compare the force reduction after the performance of a dynamic exercise configured with different ROMs.

Methods. Nine women (mean \pm standard deviation: age: 24.2 \pm 3.5 years; height: 166.5 \pm 4.1 cm; body mass: 68.35 \pm 4.14 kg) with no strength training experience and no history of injury performed (cross-over design) tests of 1RM with a knee extension machine in the following ROMs: 100–65° of knee flexion (INITIAL_{ROM}), 65–30° (FINAL_{ROM}), and 100–30° (FULL_{ROM}) (0° = knee full extended). Further, the volunteers performed, in each ROM, 3 sets of 7 repetitions at 60% of 1RM (specific to ROM assessed) with 3-minute rests between sets with 2 seconds for concentric and eccentric phases. Before and 2 minutes after the training, the maximum torque values at 100° and 30° of knee flexion were registered to calculate the force reduction.

Results. The ANOVA test identified that the maximum torque pre-training values were greater than the post-training values (p = 0.02), and a greater torque reduction occurred at 30° of knee flexion than at 100° (p = 0.001).

Conclusions. The results suggest that ROM may influence maximum strength performance, and the force may reduce similarly along the angles.

Key words: muscle strength, range of motion, joint, fatigue, torque

Introduction

Range of motion (ROM) can be defined as the angular distance travelled by a body joint [1]. Across a ROM, the muscle varies its length [2], being able to influence instantaneously its torque production capacity [3]. In addition, the resistance torque may also be altered along the ROM by increasing or diminishing the external arm moment [4]. Considering that the torque production capacity and the resistance torque are influenced by ROM, few studies compared the maximum strength performance with the one-repetition maximum (1RM) test using different ROMs for the same exercise [5–7].

In these studies, the full ROM (FULL_{ROM}) and the final partial ROM (final half of the angles of a FULL_{ROM}, considering the concentric muscle action as reference: FINAL_{ROM}) were used for the comparison. The result of this comparison indicated that a greater amount of weight could be lifted with the FINAL_{ROM} in contrast to FULL_{ROM}. It is worth noting that the exercises used in those studies (squat or bench press) offer greater external arm moment (in the knee and hip for squat, and shoulder for bench press) nearby the beginning

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of the concentric muscle action and not at the end. This may have negatively influenced the maximum weight lifted during the 1RM test for the FULL_{ROM} in comparison to FINAL_{ROM} [5]. If the external arm moment is a determining factor for strength performance, then in an exercise with a greater external arm moment at the end of the concentric action, such as with a knee extension machine, the comparison of the 1RM test performance between FULL_{ROM} and FINAL_{ROM} could show a similar result, but this reasoning has yet to be confirmed.

Additionally, prior studies [5–7] did not compare the 1RM test performance with $FULL_{ROM}$ and the initial partial ROM (initial half of the angles of a FULL_{ROM}, considering the concentric muscle action as reference: INITIAL $_{ROM}$). In the knee extension exercise, perhaps the 1RM test performance with INITIAL_{ROM} would be greater than with $FULL_{ROM}$, as the greater external arm moment is located at the final and not at the initial angles of a FULL_{ROM}. However, this reasoning has not yet been tested. Knowing whether ROM influences the strength performance may help coaches to prescribe specific training loads in order to develop the ROM in which the sport modality occurs. Also, coaches may start the exercise in a determined ROM and finish it in another ROM, as the exercise could keep being performed in the ROM in which the fatigue is lesser, expanding the training volume. In addition, males and females may present different patterns of strength response across the same joint angles [8]. Previous research compared the maximum dynamic strength performance in the $\ensuremath{\mathsf{FINAL}}_{\ensuremath{\mathsf{ROM}}}$ and $\ensuremath{\mathsf{FULL}}_{\ensuremath{\mathsf{ROM}}}$ with men [5–7]; thus, new studies with women are necessary.

In addition to the external arm moment, muscle length is another variable influenced by ROM. Exercising in different muscle lengths may alter biomechanical and physiological responses [8–11]. Kooistra et al. [9] showed that greater maximum oxygen consumption occurred at a bigger muscle length (90° of knee flexion – 0° = full knee extension) than at a smaller muscle length (30° of knee flexion) during isometric contractions. In another study, Kooistra et al. [12] demonstrated that greater time under tension could be held at a smaller than at a bigger muscle length (30° and 90° of knee flexion, respectively) in isometric contractions. These results indicate that contractions with a bigger muscle length could be more fatiguing than those with a smaller muscle length, at least in isometric contractions.

However, previous studies [9, 12] did not verify if the muscle fatigue would be also greater at a bigger than

at a smaller muscle length after a dynamic exercise performed in different ROMs, such as the INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}. As the angle manipulation during the muscle contractions can bring different physiological responses, e.g. maximum oxygen consumption levels [9, 12], it is expected that different levels of muscle fatigue may also be found when ROM is manipulated in a dynamic exercise. It has been accepted that muscle fatigue can be identified by a reduction in the ability to produce force [8, 13, 14]. Thus, dynamic contractions in different muscle lengths (i.e., different ROMs) could induce different levels of force reduction. This reasoning, though, has yet to be tested, in particular with women, as this public appears to be more susceptible to muscle injury when submitted into fatigue conditions in comparison with men [8]. Then, the information whether ROM impacts force reduction could help coaches, for example, to prescribe longer or shorter pauses for recovery during the training in an attempt to adjust the objectives desired, considering the muscle fatigue resulting from ROM manipulation.

In addition, some studies have pointed the existence of a specific increase in force production mainly in the angles trained or near them [5, 15, 16], but the mechanics behind this specific effect has not yet been elucidated. A factor that could be linked to this adaptation would be specific fatigue caused only in the angles trained. This expectation is in accordance with observations by Rhea et al. [6] that strength improvement was specific to joint angles that were sufficiently overloaded. As the overload from training may lead to acute muscle fatigue [14] and chronic adaptations such as strength increase [17], perhaps angle-specific muscle fatigue can be found when the muscle is submitted to overload in a particular ROM. As the force reduction is considered a sign of muscle fatigue [8, 13, 14], the comparison of force reduction between angles after the performance of a dynamic exercise, as with a knee extension machine, with different ROMs, such as the INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}, may provide evidence of an angle-specific fatigue effect that could contribute to explaining the strength increase within the angles trained [17].

Therefore, the present study aimed to compare strength performance in women by a 1RM test with a knee extension machine among different ROMs, and to compare the force reduction after the performance of a dynamic exercise configured with different ROMs.

Material and methods

Participants

The study sample was composed of 9 women with no strength training experience, or who had not been training for at least a year, and no history of injury (mean \pm standard deviation: age: 24.2 \pm 3.5 years; height: 166.5 \pm 4.1 cm; body mass: 68.35 \pm 4.14 kg). The sample size was calculated with the G*Power (3.1.9.2) software; the recommendations by Beck [18] were followed, as well as a study with a similar purpose [19] that presented an effect size of 0.59 for the absolute torque reduction after an induction, with an a priori statistical power (1 – β) of 0.8, a 5% significance level, 3 groups (INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}) for ANOVA (repeated measures, within factors). Before the participation in the study, the women were informed on the procedures, risks, and benefits of the investigation.

Design and procedures

This study used a crossover design to compare the 1RM test performance among 3 different ROM configurations (INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}) with a knee extension machine, and to compare the force

reduction in 2 angles, by torque values, after the execution of 3 training protocols differentiated by ROM (INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}). Each volunteer presented to the laboratory on 4 different days (experimental sessions 1–4), separated by at least 48 hours (Figure 1).

In the first session, after the assessment of height and body mass with a stadiometer (precision of 1 mm and 100 g, respectively) (Welmy[®], São Paulo, Brazil), the participants were positioned on a knee extension machine (Master[®], Belo Horizonte, Brazil). The angle of the trunk and hip was set at 110°, and the participant's ankle touched the machine cushion at 2 cm above the ankle medial malleolus. All positions were registered for the following sessions. Afterwards, the volunteers were familiarized with the 1RM test in 3 ROMs (order balanced among the ROMs). The first ROM was the INITIAL_{ROM}, and the women had to extend the knee from 100° to 65° (0° = knee full extended). The second ROM was the $FINAL_{ROM}$, and the women extended the knee from 65° to 30°. The third ROM was the $FULL_{ROM}$, and the volunteers extended the knee from 100° to 30°. Figure 2 shows the 3 ROMs used.

The 1RM test was performed during the first 2 sessions with the aim to familiarize the participants



1RM – one-repetition maximum, MVIC – maximum voluntary isometric contraction

* The 1RM tests and the angles of MVIC were balanced between the ROMs (INITIAL_{ROM}, FINAL_{ROM}, FULL_{ROM}) and angles (30° and 100° of knee flexion), respectively.

Figure 1. Experimental design



with its procedures and to define the weight (intensity) for the following procedures, respectively. In the first session, the volunteers performed the 1RM familiarization tests in each ROM presented in Figure 1. A 30-minute interval was given between the 1RM familiarization tests. For all tests, a maximum number of 6 attempts were allowed, in which the weight was gradually increased (minimum of 1 kg), with a 3-minute rest between each attempt. When the participant could not perform the concentric action within the determined ROM, the prior weight lifted was recorded, representing the 1RM test result. When the volunteers performed the FINAL_{ROM}, the machine weight support was lifted by a manual lifter (jack; Figure 2A) until the desired height that allowed the woman start the concentric action in 65° of knee flexion without any previous leg acceleration. Ten minutes after the last 1RM familiarization test, the participant was instructed to perform 2 maximum voluntary isometric contractions (MVICs) at 30° and 100° of knee flexion with a 2-minute interval between the attempts, aiming at MVIC familiarization. For the MVIC at 30°, the machine weight support was also lifted by the jack until the adequate height.

Additionally, in front of the knee extension machine, a metal apparatus was placed. When the volunteer extended the knee until the desired angle, the metal apparatus was hit by a metallic protractor that was connected to the machine nearby the cushion (Figure 2B). The metal gave the participant a visual feedback denoting the exact moment to end the concentric action during the test, and other procedures were further explained. It is worth noting that for INITIAL_{ROM}, a small bell (Figure 2B) was connected to the metal apparatus, as the participant could not see properly when the apparatus was hit by the metallic protractor at this angle. Hence, the women could listen to the bell ring and stop the knee extension to beyond 65° of knee flexion. In addition, a mirror was placed at the left side

(B) FINAL_{ROM} – final partial range of motion (C) FULL_{ROM} – full range of motion

of the apparatus to ensure full visualization of all ROMs tested. On the ground and the machine cables, tape marks were glued. The alignment of these tape marks (ground with cable) indicated the end of the eccentric action and the beginning of the concentric action, which could be seen in the mirror (Figure 3).



Figure 3. Structures used to control the range of motion: (A) mirror, jack, the ground tape mark, and the metal

- apparatus to control the end of the concentric action at 30° of knee flexion (B) metal apparatus for the end of the concentric action
- at 65° of knee flexion, the bell, the metal protractor, and the machine cable tape mark

In the second session, the participants performed the 1RM test in 1 of the 3 proposed ROMs, following the order and procedures of the familiarization tests. The intraclass correlation coefficient ($ICC_{3,1}$) was used to check the consistency of the measurement between the results from the tests and familiarization. The $ICC_{3,1}$ equalled 0.94 for INITIAL_{ROM}, 0.93 for FINAL_{ROM}, and 0.94 for FULL_{ROM}. After the 1RM test, there was a 10-minute rest. In sequence, the participant performed 2 MVICs at 30° and at 100° of knee flexion (order balanced) with a 30-second and 2-minute interval between the attempts and between the angles, respectively. After the 4 MVICs (2 in each angle), another 10-minute break was given, and the volunteers performed a training protocol. The training protocol was composed of 3 sets of 7 repetitions at 60% of the weight lifted in the 1RM test, in the ROM specifically used on that day. Additionally, a 3-minute rest was provided between the sets. The repetition duration was determined in 4 seconds (2 seconds for both concentric and eccentric muscle action) with the aid of a metronome, 60 b \cdot min⁻¹. Before starting the training protocol, each volunteer performed 10 repetitions with no load, respecting the ROM and repetition duration determined. This procedure aimed at ROM and repetition duration familiarization. The training load was defined in a previous pilot study with a similar sample and ROMs. Two minutes after the training protocol execution, the volunteers performed another 2 MVICs at 30° and at 100° of knee flexion, following the previous procedures to verify the force reduction.

Two and 4 days after the second session, the women repeated the same procedures, but in the remaining 2 ROMs (third and fourth session, respectively). All tests were individually performed on the same day time.

Regarding the MVIC values, a load cell (type S, Tedea) with a voltage range of +10 V to -10 V and capacity to support up to 500 kg was connected in series with the machine weight support cable, with the aim to record the instantaneous force during the MVIC. For the acquisition and treatment of all signals, a specific program was used (DASYLab 11.0, Ireland) with a sampling frequency of 2000 Hz. The load cell data were filtered with a 10-Hz low-pass filter, second order of the Butterworth type, which allowed to obtain force information. To calculate the MVIC torque, the force value obtained by the load cell was multiplied by the distance between the point of applying force on the machine (cushion) and the machine rotation axis (aligned with the volunteer's knee). The greater MVIC torque between the 2 attempts in each condition (pre- and post-training) at each angle (30° and 100°) was used for comparison. The ICC_{3,1} between the 2 MVIC torque attempts at 30° and 100° was 0.97 and 0.99, respectively.

Statistical procedures

The 1RM test performance in the 3 ROMs was compared via a one-way analysis of variance (ANOVA) with repeated measures (factor 1: ROM). To compare the force reduction, absolute and relative MVIC torque values were used. For the absolute comparison, a threeway ANOVA with repeated measures was applied [factor 1: ROM (INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}); factor 2: time (pre- and post-training protocols performance); factor 3: angle (30° and 100°)]. The relative comparison (%) was based on a two-way ANOVA with repeated measures [factor 1: ROM (INITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}); factor 2: angle (30° and 100°)].

For all statistic tests, the significance level was set at 0.05 and, when necessary, the post-hoc Bonferroni test was used. The effect size of ANOVA was reported by eta-squared (η^2 ; 0.01 = small, 0.06 = medium, 0.13 = large) [20]. Complementarily, the observed power for each factor in ANOVA was also reported. In addition, the effect size of each training protocol for torque values (pre to post) was reported by Cohen's d (post – pre / standard deviation of pre values; trivial: < 0.20, small: 0.20-0.60, moderate: 0.61-1.20, large: 1.21-2.0, very large: > 2.0 [21]. For all statistical analyses, the Statistical Package for the Social Sciences (SPSS 22.0) software was used. It is worth noting that previously, the repeated measure analyses: the normality, homogeneity, and sphericity of data were confirmed, respectively, by the Shapiro-Wilk, Levene, and Mauchly tests (p > 0.05).

Ethical approval

The research related to human use has complied with all the relevant national regulations and institutional policies, has followed the tenets of the Declaration of Helsinki, and has been approved by the ethics committee of the Federal University of Minas Gerais in Brazil (No.: 1758518.1.0000.5149).

Informed consent

Informed consent has been obtained from all individuals included in this study.

Results

Regarding the 1RM test performance in the 3 ROMs, the one-way ANOVA test showed a main effect for ROM $(F_{2.16} = 6.959; p = 0.007; \text{power} = 0.87; \eta^2 = 0.21)$. According to the post-hoc test, the weight lifted during the 1RM test for FINAL_{ROM} was similar to that for INITIAL_{ROM}, and both were significantly greater than the value for FULL_{ROM}. Figure 4 presents the 1RM test performance with each ROM.

Considering the absolute MVIC torque values, a main effect was only observed for time ($F_{1,8} = 19.979$; p = 0.002; power = 0.97; $\eta^2 = 0.02$) and angle ($F_{1,8} =$ 43.713; p < 0.001; power > 0.99; $\eta^2 = 0.38$). According to the post-hoc test, the pre-training torque values were greater than the post-training torque values, and the torque value produced at 100° of knee flexion was greater than that at 30°. No interaction or other main effect was detected by the three-way ANOVA with repeated measures. Table 1 shows the MVIC torque values before and after each training protocol in the 2 angles investigated, and the effect size by Cohen's d.

As for the relative MVIC torque reduction, the twoway ANOVA with repeated measures found only a main effect for angle ($F_{1,8}$ = 7.053; p = 0.029; power = 0.64; $\eta^2 = 0.02$). The post-hoc test indicated that the percentage of torque reduction was greater at 30° than at 100° of knee flexion. No interaction effect was found. Figure 5 depicts the percentage of MVIC torque reduction for each training protocol and angles.



INITIAL_{ROM} - initial partial range of motion, FINAL_{ROM} - final partial range of motion, FULL_{ROM} – full range of motion

* different from FULL_{BOM}

Figure 4. One-repetition maximum test in 3 ranges of motion



 $INITIAL_{ROM}$ – initial partial range of motion, $FINAL_{ROM}$ – final partial range of motion, FULL_{ROM} – full range of motion * greater torque reduction at 30° than at 100° of knee flexion (main

effect)

Figure 5. Percentage of torque reduction at 30° and 100° of knee flexion after the performance of protocols with different ranges of motion

Amala	Training protocols			
Angle		INITIAL _{ROM}	FINAL _{ROM}	FULL _{ROM}
30°#	Pre* Post	107.73 ± 24.43 103.76 ± 23.56	133.32 ± 33.06 110.65 ± 17.83	115.79 ± 25.40 101.94 ± 27.47
Effect size (Cohen's <i>d</i>)		0.16 (trivial)	0.69 (moderate)	0.55 (small)
100°	Pre* Post	168.40 ± 33.53 154.99 ± 36.16	169.73 ± 45.01 156.42 ± 27.85	162.47 ± 36.56 153.76 ± 39.21
Effect size (Cohen's <i>d</i>)		0.40 (small)	0.30 (small)	0.24 (small)

Table 1. Pre- and post-training isometric torque (N \cdot m) values in different ranges of motion protocols

INITIAL_{ROM} – initial partial range of motion, FINAL_{ROM} – final partial range of motion, FULL_{ROM} – full range of motion * different from post-training values, # different from 100° of knee flexion

Discussion

The objective of the present study was to compare the performance in the 1RM test in 3 different ROMs in women, and the force reduction at 30° and 100° after the performance of training protocols with different ROMs (the same as in the 1RM tests). This is the first study that compared the 1RM test results obtained in the $INITIAL_{ROM}$, $FINAL_{ROM}$, and $FULL_{ROM}$, and the force reduction in different knee joint angles after a training session in the NITIAL_{ROM}, FINAL_{ROM}, and FULL_{ROM}. According to the main results, there was no difference in the 1RM test performance between the INITIAL_{ROM} and $FINAL_{ROM}$, and these 2 ROMs presented greater performance than FULL_{ROM}. Regarding the force reduction, the performance of training the protocols differentiated by ROM provoked significant reductions at 30° and 100°, with no difference among the ROMs. In addition, the force reduction at 30° was greater than at 100°.

The INITIAL_{ROM} and FINAL_{ROM} presented similar 1RM test values, which could be explained by biomechanical factors. It has been seen that at ca. 70° of knee flexion (0° = knee fully extended), the muscle is found at or near optimal length for torque production in a knee extension machine [22]. In this case, when the volunteers started the 1RM test in the FINAL_{ROM} (65° of knee flexion), the quadriceps femoris muscle was near the optimal length to produce force in comparison with the condition of INITIAL_{ROM} (100° of knee flexion). Thus, a greater initial acceleration might have been imposed to leave the inertia for FINAL_{ROM} than for INITIAL_{ROM}, which facilitated overcoming the overload in the following angles.

However, although at $FINAL_{ROM}$, the test started with a better muscle length to produce force than at INITIAL_{ROM}, the volunteers encountered a greater external arm moment than at INITIAL_{ROM} [3]. An increase of the external arm moment demands an increase in the force production [23]. Thus, despite the volunteers started the concentric action at a better muscle length to produce force with FINAL_{ROM} than with INITIAL_{ROM}, the external arm moment was also greater with FINAL_{ROM}. On the other hand, with INITIAL_{ROM}, the volunteers started the 1RM test with a poorer force production capacity, but encountering a shorter external arm moment than with FINAL_{ROM}. The combination of greater or lower torque capacity at the beginning of the concentric action with a greater or shorter external arm moment at the end of the concentric action for FINAL_{ROM} and INITIAL_{ROM}, respectively, balanced the 1RM test results between these ROMs.

Conversely, with FULL_{ROM}, the women lifted significantly less weight than with the other 2 ROMs. The sum of the angles from INITIAL_{ROM} and FINAL_{ROM} being performed sequentially indicates that the participants had to initiate the concentric action with lesser torque production capacity than with FINAL_{ROM}, and had to overcome a greater external arm moment at the final angles of ROM than with INITIAL_{ROM}. Moreover, the rise in angular distance excursed led to an increase of the mechanical work (force × displacement). It has been observed that an increase in the mechanical work diminishes the ability to sustain a force task [24], which helps explain why the women lifted less weight at FULL_{ROM} than at the other 2 ROMs.

Regarding the force reduction results, the main effect for time showed that the training protocols performed in the 3 ROMs were similarly efficient to reduce the force production in the angles tested. Under fatigue conditions, the force reduction could be associated with many physiological alterations [25]. The accumulation of intracellular hydrogen ions may impair the function of the contractile proteins: ionic changes in the action potential and failure of sarcoplasmic reticulum Ca^{2+} release are factors associated with fatigue [13]. In addition, a greater force depression was noticed at 30° of knee flexion in comparison with 100°. It means that the force production capacity at 30° was more affected by the training protocols than at 100°.

Although the present study did not aim to provide information regarding possible mechanisms involved in force reduction response, it is possible to speculate that the physiological differences of contracting in different muscle lengths may have caused the distinct force reduction responses between angles. When a muscle is lengthened, the Ca²⁺ sensitivity increases [26]. Thus, the force reduction due to the decrease of Ca²⁺ release in fatigue conditions would be minimized when the muscle is demanded to contract at a bigger length than at a smaller one. This suggestion is supported by the findings by MacNaughton et al. [27], who demonstrated a greater decrease of active force at a small muscle length in comparison with optimal muscle length. Moreover, at a bigger muscle length, less overlapping of actin and myosin is expected to occur than at a smaller muscle length [10]. Less overlapping of actin and myosin means that less adenosine triphosphate becomes hydrolysed and, consequently, less accumulation of metabolic ions related to muscle fatigue (P_i, P_{cr}, H⁺) occurs [17]. This reasoning could help explain why greater force reduction was observed at 30° than at 100° of knee flexion; however, it is speculative.

Another explanation is perhaps linked to the findings by Joumaa et al. [28], who demonstrated a change in the actin filament conformational structure after active shortening, which could inhibit the cross-bridge attachment and muscle stiffness. According to Chen et al. [25], the reduction of the number of cross-bridges after active contractions is the main factor in force reduction. Thus, the decrease of the number of crossbridge attachments after the training protocols, caused by the change in the actin structure, may have influenced muscle force production more at 30° of knee flexion (smaller muscle length) than at 100° (bigger muscle length) as the passive force offers greater force contribution at a bigger muscle length than at a smaller one [10]. In this case, perhaps a greater time for recovering of the maximum force production at a smaller than at a bigger muscle length would be necessary after resistance training, regardless of the ROM adopted, but further studies are required to clarify this issue.

Nevertheless, the production of the knee extension torque is derived from the sum of the torque produced from each quadriceps muscle [3], and the change in the knee joint angle may impact on the length and the torque production of each muscle differently [12]. Akima et al. [11] demonstrated greater muscle fatigue (decrease of electromyographic median frequency) of the vastus lateralis muscle during 40 isometric contractions with the knee flexed (100°) than extended (40°) (0° = knee full extended). This response was not followed by the other muscles; e.g., the rectus femoris muscle presented similar fatigue during contractions in either angle. Further investigation is needed to verify whether individual muscle torque production is influenced by dynamic contractions in different ROMs.

No interaction between the factors of angle and ROM was found. It was expected that greater force depression would occur at the angles excursed during the training with the protocols. This expectation was based on the results of studies that showed a specific force increase only at or near the angles trained [5, 15, 16]. However, it has been reported that fatigue is not a necessary stimulus for strength gains [29, 30], and perhaps the angle-specific force increase is not linked to fatigue [30]. Our results support this rationale as angle-specific fatigue was not seen in the present study, but a longitudinal study is needed to confirm this line of reasoning.

Other results from ANOVA revealed that greater isometric force was produced at 100° than at 30° of knee flexion. This is in line with another study [11]. At 100° of knee flexion, a greater passive force can be produced and transmitted by the muscle-tendon unit than at 30°, contributing to the achievement of a greater amount of force production from the sum of passive and active forces [8, 11].

Notwithstanding, the results from the present study refer to females, and may not be extrapolated to men owing to the physiological and biomechanical differences between genders [14], specially under fatigue [8]. This is a limitation of the study, and further research needs to be conducted in men to improve the understanding of the effect of ROM on strength performance.

Conclusions

The present study showed that the performance of training protocols differentiated by ROM led to similar isometric force reduction, regardless of the angle tested. Besides, greater force reduction occurred at 30° than at 100° of knee flexion, irrespective of the training protocol, and greater amount of weight was lifted in the 1RM test in the training protocols with partial ROMs as compared with FULL_{ROM}.

Disclosure statement

No author has any financial interest or received any financial benefit from this research.

Conflict of interest

The authors state no conflict of interest.

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